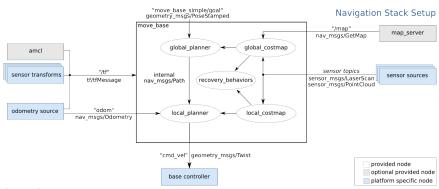# CS354

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October 17, 2017

gmapping

- http://wiki.ros.org/gmapping ↗
- This is just a thin ROS-wrapper around
    - http://openslam.org/gmapping.html ↗

Navigation

Navigation Stack Setup

http://wiki.ros.org/navigation/Tutorials/RobotSetup

- **Publish/Subscribe** - best for sharing streaming data
- **Services** - remote procedure calls, send a request, wait for result

- Publish/Subscribe - best for sharing streaming data
- Services - remote procedure calls, send a request, wait for result

- Sometimes we want to request a long-running service, then get on with things, potentially cancelling the request later:
    - actionlib
    - http://wiki.ros.org/actionlib ↗

action_nav.py