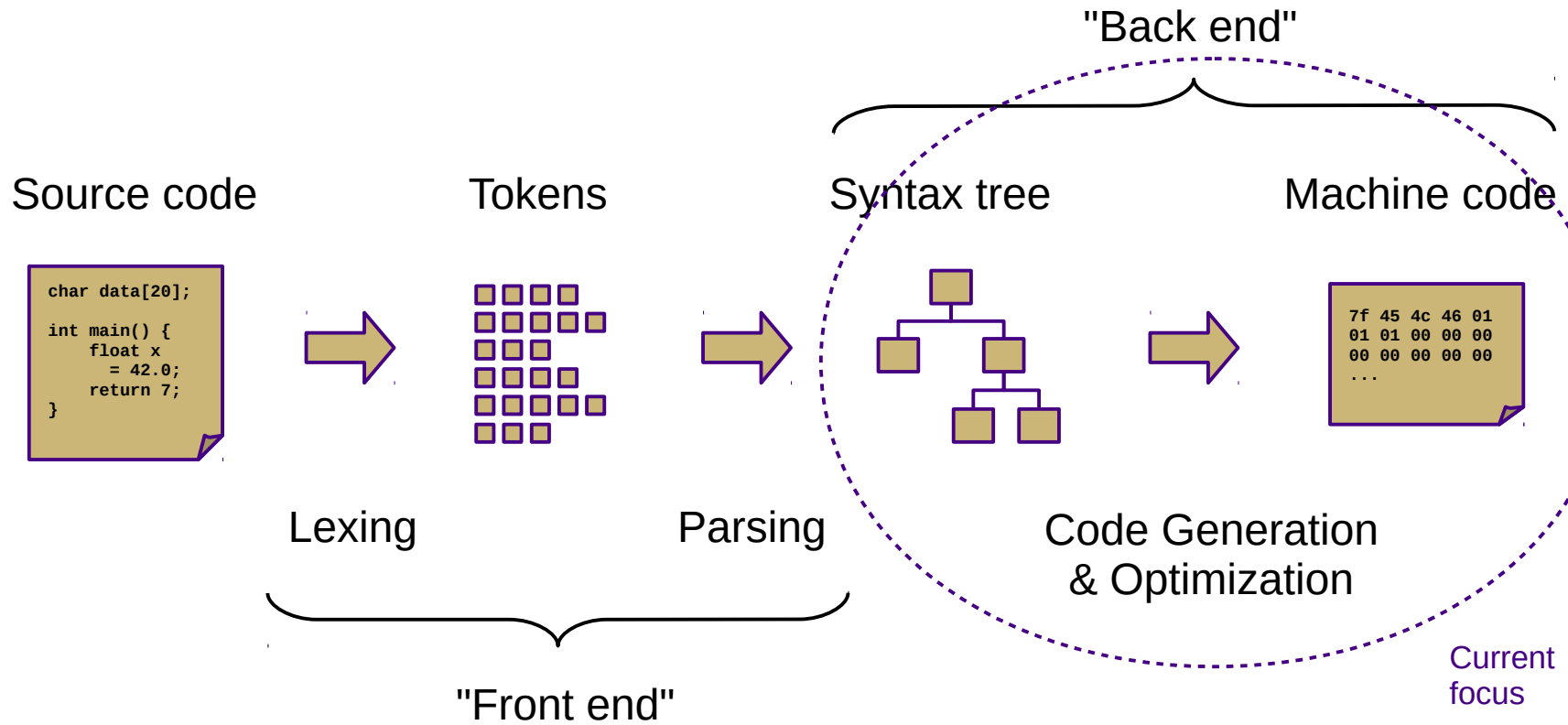


CS 432
Fall 2016

Mike Lam, Professor

Data-Flow Analysis

Compilers



Optimization is Hard

- **Problem:** it's hard to reason about all possible executions
 - Preconditions and inputs may differ
 - Optimizations should be correct and efficient in all cases
 - Consider this code:

```
int *p; cin >> p; *p = 42;
```
- Optimization tradeoff: **investment vs. payoff**
 - "Better than naïve" is fairly easy
 - "Optimal" is impossible
 - Real world: somewhere in between
 - Better speedups with more static analysis
 - Usually worth the added compile time

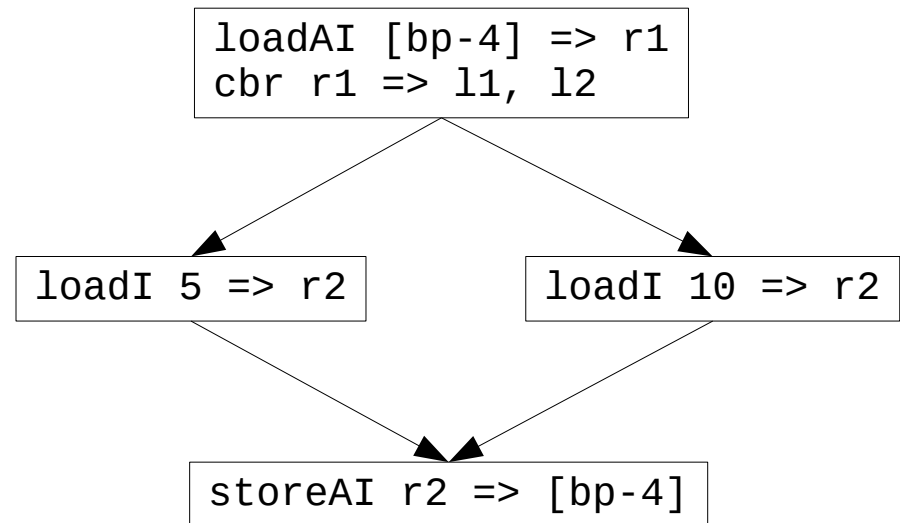
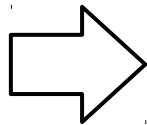
Control-Flow Graphs

- Linear IRs (e.g., ILOC) don't easily expose control flow
 - This makes analysis and optimization difficult
- **Basic blocks**
 - "Maximal-length sequence of branch-free code"
 - "Atomic" code sequences
 - Instructions that always execute together
- **Control-flow graph (CFG)**
 - Nodes/vertices for basic blocks
 - Edges for control transfer
 - Branches (explicit) or fallthrough (implicit)
 - p is a **predecessor** of q if there is a path from p to q
 - q is a **successor** of p if there is a path from p to q

Control-Flow Graphs

- Conversion: linear IR to CFG
 - Find **leaders** (initial instruction of a basic block) and build blocks
 - Every call or jump target is a leader
 - Add edges between blocks based on branches and fallthrough
 - Complicated by jump-to-address instructions

```
foo:  
  loadAI [bp-4] => r1  
  cbr r1 => 11, 12  
11:  
  loadI 5 => r2  
  jump 13  
12:  
  loadI 10 => r2  
13:  
  storeAI r2 => [bp-4]
```



Static CFG Analysis

- Single block analysis is easy
- Trees are also relatively easy
 - No path merges or loops
- General CFGs are harder
 - Which branch of a conditional will execute?
 - How many times will a loop execute?
- How do we handle this?
 - One method: iterative **data-flow analysis**
 - Simulate all possible paths through a region of code

Data-Flow Analysis

- Define **properties** of interest for basic blocks
 - Usually **sets** of blocks, variables, definitions, etc.
- Define a **formula** for how those properties change within a block
 - $F(B)$ is based on $F(A)$ where A is a predecessor or successor of B
- Gather **initial information** to help calculate property changes
 - Helper functions $g(B)$ that can be used in $F(B)$
- Run an **iterative update** algorithm to propagate changes
 - Keep running until the properties converge for all basic blocks
 - More efficient w/ **reverse postorder** traversal: visit predecessors first
- Key concept: **finite descending chain property**
 - Properties must be monotonically increasing or decreasing
 - Otherwise, termination is not guaranteed

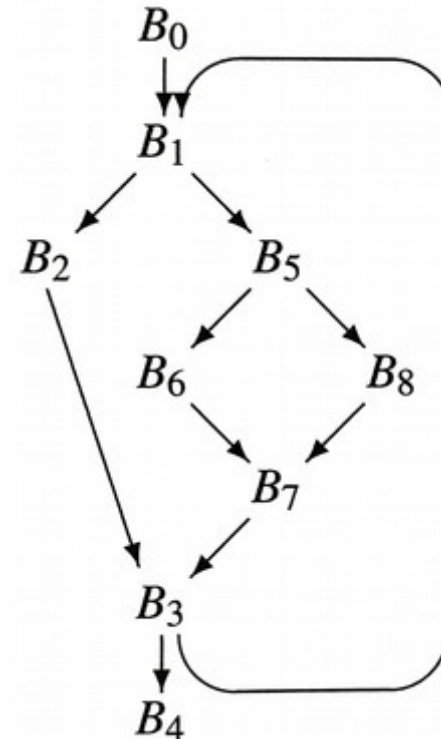
Data-Flow Analysis

- This kind of algorithm is called a **fixed-point algorithm**
 - It runs until it converges to a “fixed point”
- **Forward** vs. **backward** data-flow analysis
 - Forward: along graph edges (based on predecessors)
 - Backward: reverse of forward (based on successors)
- Types of data-flow analysis
 - **Dominance**
 - **Liveness**
 - Available expressions
 - Reaching definitions
 - Anticipable expressions

Dominance

- Block A **dominates** block B if A lies on every path from the entry block to B
 - Conversely, B **postdominates** block A if B lies on every path from A to any exit

$$Dom(n) = \{n\} \cup \left(\bigcap_{m \in preds(n)} Dom(m) \right)$$



Liveness

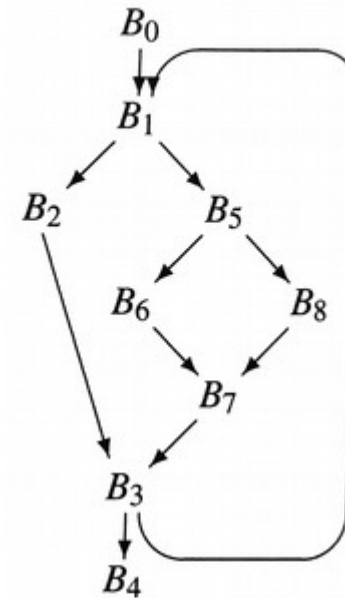
- Variable v is **live** at point p if there is a path from p to a use of v with no intervening assignment to v
 - Useful for finding uninitialized variables (live at function entry)
 - Useful for optimization (remove unused assignments)
 - Useful for register allocation (keep live vars in registers)
- Initial information: **UEVar** and **VarKill**
 - UEVar(B): variables used in B before any redefinition in B
 - VarKill(B): variables that are defined in B
- Textbook note: $X \cap \bar{Y} = X - Y$

$$LiveOut(n) = \bigcup_{m \in succs(n)} (UEVar(m) \cup (LiveOut(m) - VarKill(m)))$$

Liveness example

B_0 : $i \leftarrow 1$
 $\rightarrow B_1$
 B_1 : $a \leftarrow \dots$
 $c \leftarrow \dots$
 $(a < c) \rightarrow B_2, B_5$
 B_2 : $b \leftarrow \dots$
 $c \leftarrow \dots$
 $d \leftarrow \dots$
 $\rightarrow B_3$
 B_3 : $y \leftarrow a + b$
 $z \leftarrow c + d$
 $i \leftarrow i + 1$
 $(i \leq 100) \rightarrow B_1, B_4$

B_4 : return
 B_5 : $a \leftarrow \dots$
 $d \leftarrow \dots$
 $(a \leq d) \rightarrow B_6, B_8$
 B_6 : $d \leftarrow \dots$
 $\rightarrow B_7$
 B_7 : $b \leftarrow \dots$
 $\rightarrow B_3$
 B_8 : $c \leftarrow \dots$
 $\rightarrow B_7$



(a) Code for the Basic Blocks

(b) Control-Flow Graph

	B_0	B_1	B_2	B_3	B_4	B_5	B_6	B_7	B_8
UEVAR	\emptyset	\emptyset	\emptyset	$\{a, b, c, d, i\}$	\emptyset	\emptyset	\emptyset	\emptyset	\emptyset
VARKILL	$\{i\}$	$\{a, c\}$	$\{b, c, d\}$	$\{y, z, i\}$	\emptyset	$\{a, d\}$	$\{d\}$	$\{b\}$	$\{c\}$

(c) Initial Information

$$LiveOut(n) = \bigcup_{m \in succs(n)} (UEVar(m) \cup (LiveOut(m) - VarKill(m)))$$

Alternative definition

- Define **LiveIn** as well as **LiveOut**
 - Two formulas for each basic block
 - Makes things a bit simpler to reason about

$$LiveIn(n) = UEVar(n) \cup (LiveOut(n) - VarKill(n))$$

$$LiveOut(n) = \bigcup_{m \in succs(n)} [LiveIn(m)]$$