CS 261
Fall 2020

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Caching
(get it??)
Topics

- Caching
- Cache implementations
- Cache policies
- Cache performance
- Performance improvement strategies
Motivation

- Caching is ubiquitous in modern computing:
  - L1-L3 memory
  - TLB and virtual memory (next week)
  - Disk controller buffers
  - Network controller buffers
  - Browser caches
  - Content delivery networks
A cache is a small, fast memory that acts as a buffer or staging area for a larger, slower memory.

- Fundamental CS system design concept
- Data is transferred in blocks or lines
- Slower caches use larger block sizes
- Cache hit vs. cache miss
- Hit ratio: \# hits / \# memory accesses
Cache implementations

• What data structure can we use to implement caches?
  − Need **FAST** lookups and containment checks
  − From CS 240: use a hash table!
  − Cache slot = "real address" % CACHE_SIZE

Multiple addresses may map to the same cache slot! (this is called a conflict)
Question

- Suppose we have a sixteen-element cache, with slots labeled starting at zero. Which slot would we use to store a cached version of a data element stored at address 0x4d6?
  - Reminder: cache slot = "real address" % CACHE_SIZE
  - Hint: $2^4 = 16$, and four bits = one hex digit
Cache implementations

- A **cache line** is a block or sequence of bytes that is moved between memory levels in a single operation.
- A **cache set** is a collection of one or more cache lines:
  - Each cache line contains a **tag** to identify the source address and a **valid** flag/bit indicating whether the value is up-to-date.

![Diagram of cache sets and lines](image)
Cache implementations

- **General cache organization:**
  - \( S = \# \text{ of cache sets} = 2^s \)
    - \( s = \# \text{ of bits for set index} \)
  - \( E = \# \text{ of lines per cache set} \)
    - Level of associativity
  - \( B = \text{block (cache line) size} = 2^b \)
    - Essentially bytes per line
    - \( b = \# \text{ of bits for block offset} \)
  - \( m = \# \text{ of bits for memory address} \)
    - \( M = \text{size of memory in bytes} = 2^m \)
  - \( C = \text{total cache capacity} = S \times E \times B \)
    - \( \text{sets} \times \text{lines/set} \times \text{bytes/line} \)
  - \( t = \# \text{ of tag bits} = m - s - b \)
Types of caches

- **Direct-mapped** ($E = 1$)
  - One line per set

- **Set-associative** ($1 < E < C/B$)
  - Multiple lines per set

- **Fully-associative** ($E = C/B$)
  - All lines in one set
Cache implementations

- **Direct-mapped** \((E = 1)\) caches
• Suppose we have a direct-mapped cache (S=16, B=1), with sets labeled starting at zero. Which set would we use to store a cached version of a data element stored at address 0x4d6?
  - Hint: S=16 so the number of bits for the set index is four
  - Hint: B=1 so the number of bits for the block offset is zero
Cache implementations

- **Set-associative** \((1 < E < C/B)\) caches

![Diagram of cache configurations]

- **Set-associative** caches allow finding cache blocks in parallel.
- **E=2 lines per set**

“Two-way set associative”

- (1) The valid bit must be set
- (2) The tag bits in one of the cache lines must match the tag bits in the address
- (3) If (1) and (2), then cache hit, and block offset selects starting byte
Question

- Suppose we have a four-way set-associative cache (S=16, E=4, B=1), with sets labeled starting at zero. Which set would we use to store a cached version of a data element stored at address 0x4d6?
Cache implementations

- **Fully-associative** \((E = C/B)\) caches

The entire cache is one set, so by default set 0 is always selected.

<table>
<thead>
<tr>
<th>Valid</th>
<th>Tag</th>
<th>Cache block</th>
</tr>
</thead>
<tbody>
<tr>
<td>Valid</td>
<td>Tag</td>
<td>Cache block</td>
</tr>
<tr>
<td></td>
<td>...</td>
<td></td>
</tr>
</tbody>
</table>

\[ E = \frac{C}{B} \] lines in the one and only set.

(1) The valid bit must be set.

(2) The tag bits in one of the cache lines must match the tag bits in the address.

(3) If (1) and (2), then cache hit, and block offset selects starting byte.
• Suppose we have a fully-associative cache (B=1) with sets labeled starting at zero. Which set would we use to store a cached version of a data element stored at address 0x4d6?
Cache implementations

- In general, we use the middle bits for the set index
  - Contiguous memory blocks should map to different cache sets
Cache misses ("Three C’s")

- **Compulsory / cold miss**
  - First cache miss due to an “empty” cache
  - As the cache loads data, it is warmed up

- **Conflict miss**
  - Cache miss due to multiple lines in working set mapping to the same cache line
  - Repeated conflict misses for the same cache lines or blocks is called **thrashing**

- **Capacity miss**
  - The **working set** (amount of memory accessed in a given time interval) is too large to fit in cache
Cache policies

• If a cache set is full, a cache miss in that set requires lines to be replaced or evicted

• Policies:
  – Random replacement
  – Least recently used
  – Least frequently used

• These policies require additional overhead
  – More important for lower levels of the memory hierarchy
Cache policies

- How should we handle writes to a cached value?
  - **Write-through**: immediately update to lower level
    - Typically used for higher levels of memory hierarchy
  - **Write-back**: defer update until replacement/eviction
    - Typically used for lower levels of memory hierarchy

- How should we handle write misses?
  - **Write-allocate**: load then update
    - Typically used for write-back caches
  - **No-write-allocate**: update without loading
    - Typically used for write-through caches
Performance impact

• Metrics
  - **Hit rate/ratio**: \# hits / \# memory accesses (1 – miss rate)
    • Hit time: delay in accessing data for a cache hit
  - **Miss rate/ratio**: \# misses / \# memory accesses
    • Miss penalty: delay in loading data for a cache miss
  - Read throughput (or "bandwidth"): the rate that a program reads data from a memory system

• General observations:
  - Larger cache = higher hit rate but higher hit time
  - Lower miss rates = higher read throughput
Case study: matrix multiply

(a) Version $ijk$

code/mem/matmult/mm.c
1 for (i = 0; i < n; i++)
2 for (j = 0; j < n; j++) {
3 sum = 0.0;
4 for (k = 0; k < n; k++)
5 sum += A[i][k]*B[k][j];
6 C[i][j] += sum;
7 }

(b) Version $jik$

code/mem/matmult/mm.c
1 for (j = 0; j < n; j++)
2 for (i = 0; i < n; i++) {
3 sum = 0.0;
4 for (k = 0; k < n; k++)
5 sum += A[i][k]*B[k][j];
6 C[i][j] += sum;
7 }

(c) Version $jki$

code/mem/matmult/mm.c
1 for (j = 0; j < n; j++)
2 for (k = 0; k < n; k++) {
3 r = B[k][j];
4 for (i = 0; i < n; i++)
5 C[i][j] += A[i][k]*r;
6 }

(d) Version $kji$

code/mem/matmult/mm.c
1 for (k = 0; k < n; k++)
2 for (j = 0; j < n; j++) {
3 r = B[k][j];
4 for (i = 0; i < n; i++)
5 C[i][j] += A[i][k]*r;
6 }

(e) Version $kij$

code/mem/matmult/mm.c
1 for (k = 0; k < n; k++)
2 for (i = 0; i < n; i++) {
3 r = A[i][k];
4 for (j = 0; j < n; j++)
5 C[i][j] += r*B[k][j];
6 }

(f) Version $ikj$

code/mem/matmult/mm.c
1 for (i = 0; i < n; i++)
2 for (k = 0; k < n; k++) {
3 r = A[i][k];
4 for (j = 0; j < n; j++)
5 C[i][j] += r*B[k][j];
6 }

Figure 6.44 Six versions of matrix multiply. Each version is uniquely identified by the ordering of its loops.
Case study: matrix multiply

Lower is better
Optimization strategies

- Focus on the common cases
- Focus on the code regions that dominate runtime
- Focus on inner loops and minimize cache misses
- Favor repeated local accesses (temporal locality)
- Favor stride-1 access patterns (spatial locality)

**Tip**: You can use Valgrind to detect cache misses (look up a tool called cachegrind)
Core theme

- **Cache system design involves tradeoffs**
  - Larger caches => higher hit rate but higher hit time
    - Size vs. speed
  - Larger blocks => higher hit rate for programs with good spatial locality, but lower hit rate for others
    - Favor spatial vs. temporal locality
  - Higher associativity => lower chance of thrashing but expensive to implement w/ possibly increased hit time
    - Hit time vs. miss penalty
  - More writes => simpler to implement but lower performance
    - Write-through vs. write-back
Next time

- **Virtual memory**: an OS-level memory cache
  - Bridge between module 4 (machine architectures) and module 5 (operating systems)
Cache architecture

- **Example:** Intel Core i7

- **Per-core:**
  - Registers
  - L1 data and instruction (d-cache and i-cache)
    - Data and instructions
  - L2 unified cache

- **Shared:**
  - L3 unified cache
  - Main memory
• As the **working set size** of a loop decreases, what generally happens to the read throughput?

- A) It increases
- B) It decreases
- C) It remains the same
- D) There is no correlation
- E) Not enough information to determine
Temporal locality

- Working set size vs. throughput
Question

- As the **stride** of a loop increases, what generally happens to the read throughput?
  - A) It increases
  - B) It decreases
  - C) It remains the same
  - D) There is no correlation
  - E) Not enough information to determine
Spatial locality

- Stride vs. throughput

![Bar chart showing read throughput in MB/s for different strides. One access per cache line is indicated with an arrow. Higher is better.]
Memory mountain (CS:APP)

- Stride and WSS vs. read throughput

Higher is better
Output of `lscpu`:

Architecture:        x86_64
Byte Order:          Little Endian
CPU(s):              24
Thread(s) per core:  2
Core(s) per socket:  6
Socket(s):           2
Vendor ID:           Intel
Model name:          Intel(R) Xeon(R) CPU E5-2640
CPU max MHz:         3000.0000
CPU min MHz:         1200.0000
L1d cache:           32K
L1i cache:           32K
L2 cache:            256K
L3 cache:            15360K
Output of `lscpu`:

- **Architecture:** x86_64
- **Byte Order:** Little Endian
- **CPU(s):** 48
- **Thread(s) per core:** 2
- **Core(s) per socket:** 12
- **Socket(s):** 2
- **Vendor ID:** Intel
- **Model name:** Intel(R) Xeon(R) CPU E5-2680
- **CPU max MHz:** 3300.0000
- **CPU min MHz:** 1200.0000
- **L1d cache:** 32K
- **L1i cache:** 32K
- **L2 cache:** 256K
- **L3 cache:** 30720K
Question

- Assume the following cache:
  - $S = 8$ sets (so $s=3$ bits for set index)
  - $E = 1$ line per set (so direct-mapped)
  - $B = 4$ bytes per line (so $b=2$ bits for block offset)
- What is the set index, tag, and block offset for address 227?
  - Hint: 227 in binary is 11100011
Question

- Assume the following cache:
  - \( S = 8 \) sets (so \( s=3 \) bits for set index)
  - \( E = 1 \) line per set (so direct-mapped)
  - \( B = 4 \) bytes per line (so \( b=2 \) bits for block offset)

- Address 227 (binary: 11100011)
  - Set index = 000\(_2\) (0)
  - Tag = 111\(_2\) (7)
  - Block offset = 11\(_2\) (3)

- **Is this a hit?**

  No! Need to load the line into cache:

<table>
<thead>
<tr>
<th></th>
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<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>0 (000)</td>
<td>1</td>
<td>111</td>
<td>m[224]</td>
<td>m[225]</td>
<td>m[226]</td>
<td>m[227]</td>
</tr>
</tbody>
</table>
Question

• Assume the following cache:
  – \( S = 8 \) sets (so \( s=3 \) bits for set index)
  – \( E = 1 \) line per set (so direct-mapped)
  – \( B = 4 \) bytes per line (so \( b=2 \) bits for block offset)

• What is the set index, tag, and block offset for address 226? Is it a hit?
  – Hint: 226 in binary is 11100010