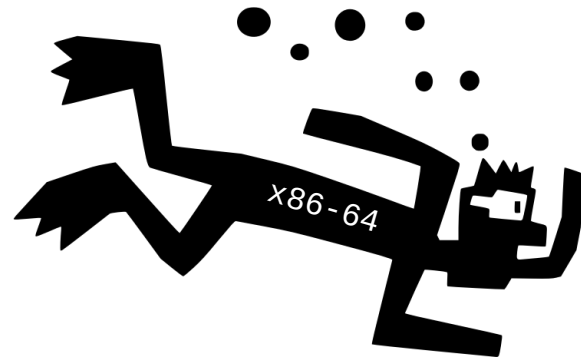


# CS 261 Fall 2019

Mike Lam, Professor

Q. Why do assembly programmers need to know how to swim?

A. Because they work below C level!



## x86-64 Data Structures and Misc. Topics

# Topics

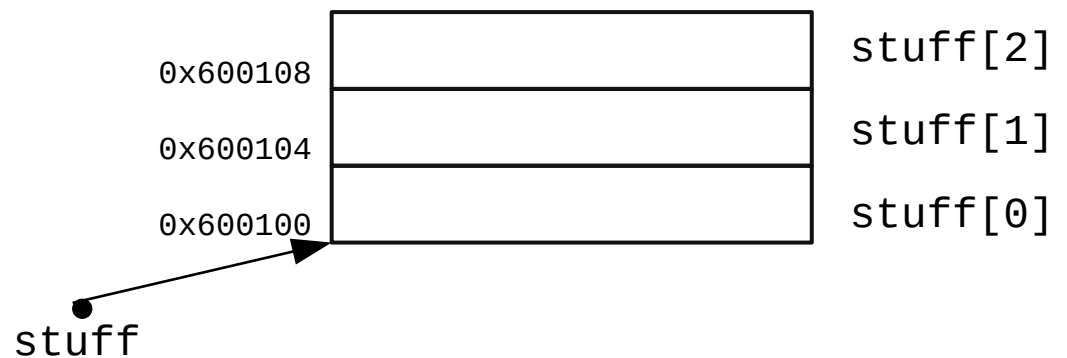
- Homogeneous data structures
  - Arrays
  - Nested / multidimensional arrays
- Heterogeneous data structures
  - Structs / records
  - Unions
- Floating-point code
- Misc. notes

# Arrays

- An **array** is simply a block of memory (*bits*)
  - Fixed-sized *homogeneous* elements of a particular type (*context*)
  - Contiguous layout
  - Fixed length (not stored as part of the array!)

```
int32_t stuff[3];
```

*3 elements  
each element is 4 bytes wide  
total size is 3 \* 4 = 12 bytes*



```
stuff[0] = 7  
stuff[1] = 7  
stuff[2] = 7
```



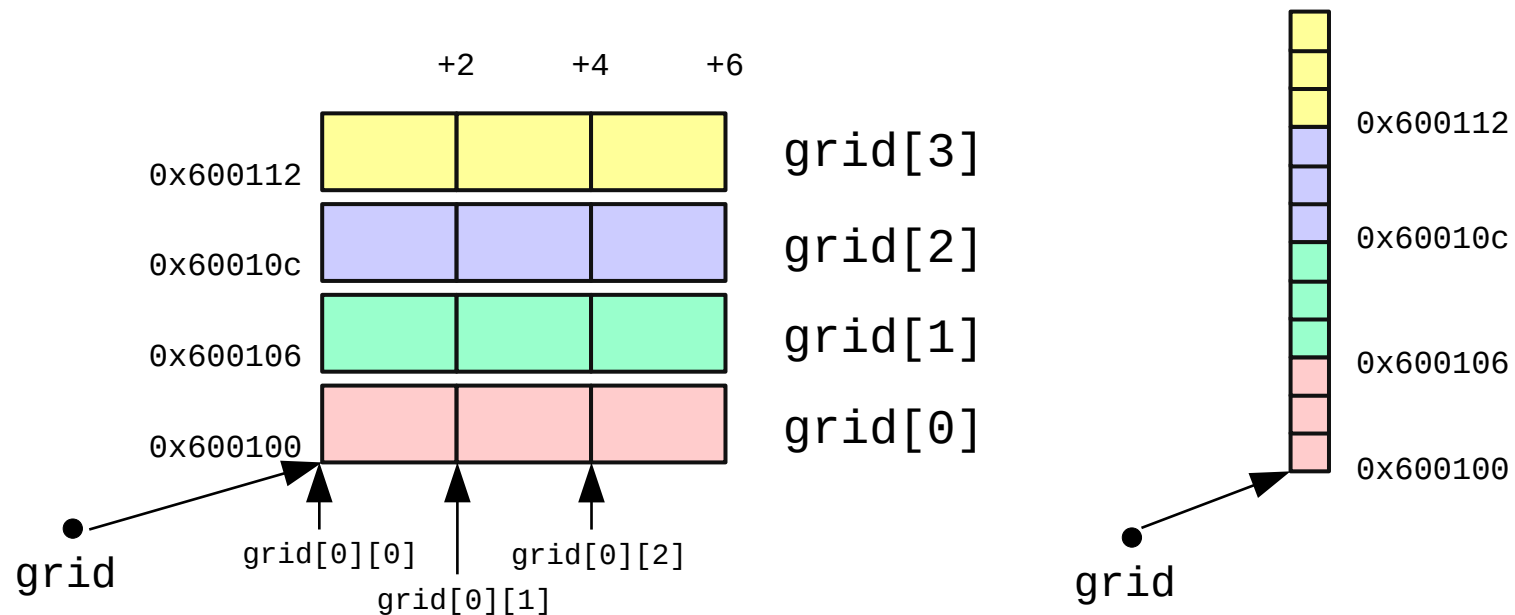
```
movq $0x600100, %rbx  
movl $7, (%rbx)  
movl $7, 4(%rbx)  
movl $7, 8(%rbx)
```

# Arrays and pointers

- Array name is essentially a pointer to first element (base)
  - The  $i$ th element is at address  $(\text{base} + \text{size} * i)$
- C **pointer arithmetic** uses intervals of the element width
  - No need to explicitly multiply by size in C
  - “stuff+0” or “stuff” is the address of the first element
  - “stuff+1” is the address of the second element
  - “stuff+2” is the address of the third element
- Indexing = pointer arithmetic plus dereferencing
  - “stuff[i]” means “\*(stuff + i)”
  - In assembly, use the scaled index addressing mode
    - $(\text{base}, \text{index}, \text{scale}) \rightarrow$  e.g.,  $(\%rbx, \%rdi, 4)$  for 32-bit elements

# Nested / multidimensional arrays

- Generalizes cleanly to multiple dimensions
  - Think of the elements of outer dimensions as being arrays of inner dimensions
  - “Row-major” order: outer dimension specified first
  - E.g., “`int16_t grid[4][3]`” is a 4-element array of 3-element arrays of 16-bit integers
  - 2D: Address of  $(i,j)$ th element is  $(\text{base} + \text{size}(\text{cols} * i + j))$
  - 3D: Address of  $(i,j,k)$ th element is  $(\text{base} + \text{size}((n_{d1} * n_{d2}) * i + n_{d2} * j + k))$

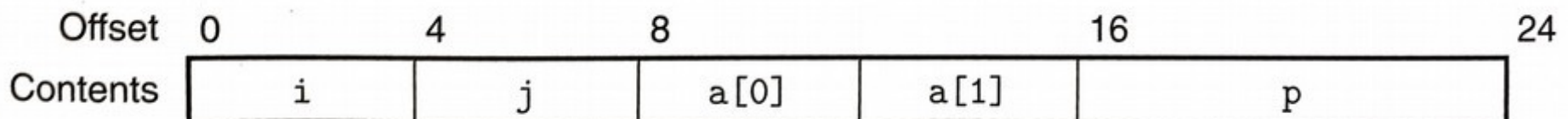


# Structs

- C **structs** are also just regions of memory
  - “Structured” *heterogeneous* regions--they’re split into fields
  - Contiguous layout (w/ occasional gaps for **alignment**)
  - Offset of each field can be determined by the compiler
  - Sometimes called “**records**” generally

```
struct {
    int i;          x.i = 1;          movl $1, (%rbx)
    int j;          x.j = 2;          movl $2, 4(%rbx)
    int a[2];       x.a[0] = 3;       movl $3, 8(%rbx)
    int *p;        x.a[1] = 4;       movl $4, 8(%rbx, %rdi, 4)
} x;              x.p = NULL;       movq $0, 16(%rbx)
```

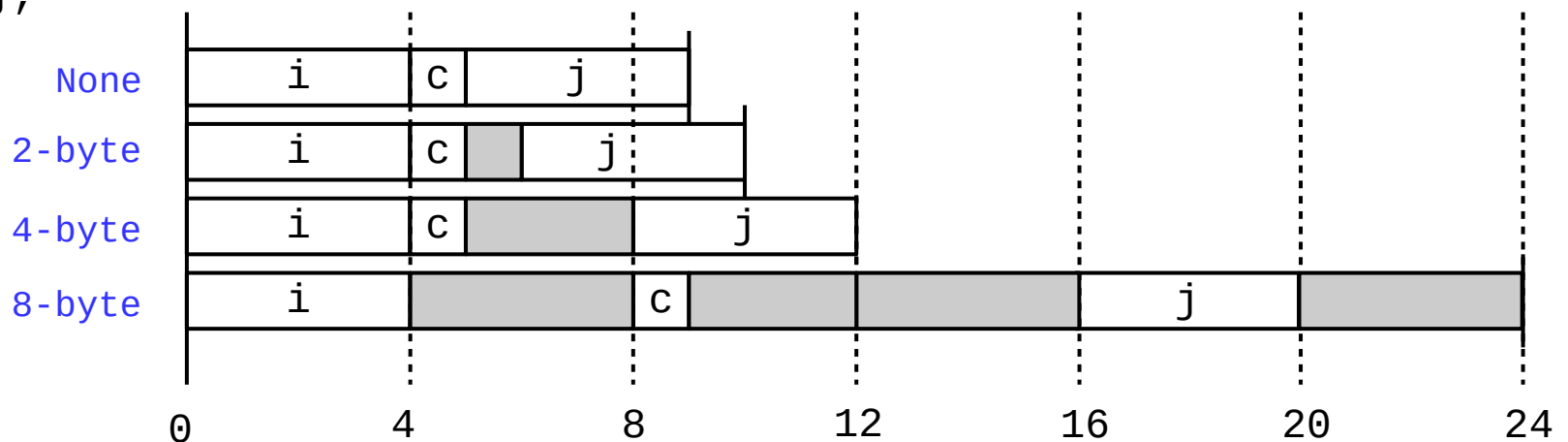
(%rbx = &x and %rdi = 1)



# Alignment

- **Alignment restrictions** require addresses be  $n$ -divisible
  - E.g., 4-byte alignment means all addresses must be divisible by 4
  - Specified using an assembler directive
  - Improves memory performance if the hardware matches
  - Can be avoided in C using “attribute (packed)” (as in `elf.h`)

```
struct {  
    int i;  
    char c;  
    int j;  
} rec;
```



# Union

- C **unions** are also just regions of memory
  - Can store one “thing”, but it could be multiple sizes depending on what kind of “thing” it currently is (so context is even more important!)
  - All “fields” start at offset zero
  - Generally a bad idea! (circumvents the type system in C)
  - Can be used to do OOP in C (i.e., polymorphism)

```
typedef enum { CHAR, INT, FLOAT } objtype_t;
```

```
typedef struct {  
    objtype_t type;  
    union {  
        char c;  
        int i;  
        float f;  
    } data;  
} obj_t;
```

```
obj_t foo;
```

```
foo.type = INT;  
foo.data.i = 65;
```

```
printf("%c", foo.data.c); ← VALID!
```



# Floating-point code

- **x87**: extension of x86 for floating-point arithmetic
  - Originally for the **8087** floating-point co-processor
  - Adds new floating-point "stack" registers **ST(0) – ST(7)**
    - 80-bit **extended double** format (15 exponent and 63 significand bits)
  - Push/pop with **FLD** and **FST** instructions
  - Arithmetic: **FADD**, **FMUL**, **FSQRT**, etc.
  - Largely deprecated now in favor of new SIMD architectures

# Floating-point code

- **Single-Instruction, Multiple-Data (SIMD)**
  - Performs the same operation on multiple pairs of elements
  - Also known as **vector** instructions
- Various floating-point SIMD instruction sets
  - MMX, **SSE**, **SSE2**, SSE3, SSE4, SSE5, **AVX**, **AVX2**
  - 16 new extra-wide XMM (128-bit) or YMM (256-bit) registers for holding multiple elements
    - Floating-point arguments passed in %xmm0-%xmm7
    - Return value in %xmm0
    - All registers are caller-saved

# Floating-point code

- **SSE** (Streaming SIMD Extensions)
  - 128-bit XMM registers
    - Can store two 64-bit doubles or four 32-bit floats
  - New instructions for movement and arithmetic
    - General form:  $\langle op \rangle \langle s|p \rangle \langle s|d \rangle$
    - $\langle s|p \rangle$ : s=scalar (single data) p=packed (multiple data)
    - $\langle s|d \rangle$ : s=single (32-bit) d=double (64-bit)
    - E.g., “addsd” = add scalar 64-bit doubles
    - E.g., “mulps” = multiply packed 32-bit floats
- **AVX** (Advanced Vector Extensions)
  - 256-bit YMM registers
    - Can store four 64-bit doubles or eight 32-bit floats
  - Similar instructions as SSE (but with “v” prefix, e.g., vmulps)

# SSE/AVX

- **Movement**

- movss / movsd
- movaps / movapd

- **Conversion**

- cvtsi2ss / cvtsi2sd
- cvtss2si / cvtsd2si
- cvtss2sd / cvtsd2ss

- **Arithmetic**

- addss / addsd
- addps / addpd
- ... (sub, mul, div, max, min, sqrt)
- andps / andpd
- xorps / xorpd

- **Comparison**

- ucomiss / ucomisd

(AVX has "v\_\_\_\_" opcodes)

255	127	0	
%ymm0	%xmm0		1st FP arg./Return
%ymm1	%xmm1		2nd FP argument
%ymm2	%xmm2		3rd FP argument
%ymm3	%xmm3		4th FP argument
%ymm4	%xmm4		5th FP argument
%ymm5	%xmm5		6th FP argument
%ymm6	%xmm6		7th FP argument
%ymm7	%xmm7		8th FP argument
%ymm8	%xmm8		Caller saved
%ymm9	%xmm9		Caller saved
%ymm10	%xmm10		Caller saved
%ymm11	%xmm11		Caller saved
%ymm12	%xmm12		Caller saved
%ymm13	%ymm13		Caller saved
%ymm14	%xmm14		Caller saved
%ymm15	%xmm15		Caller saved

# Bitwise operations in SSE/AVX

- Assembly instructions provide low-level access to floating-point numbers
  - Some numeric operations can be done more efficiently with simple bitwise operations
- AKA: Stupid Floating-Point Hacks™
  - Set to zero (value XOR value)
  - Absolute value (value AND 0x7fffffff)
  - Additive inverse (value XOR 0x80000000)
- Lesson: Information = Bits + Context
  - *(even if it wasn't the intended context!)*

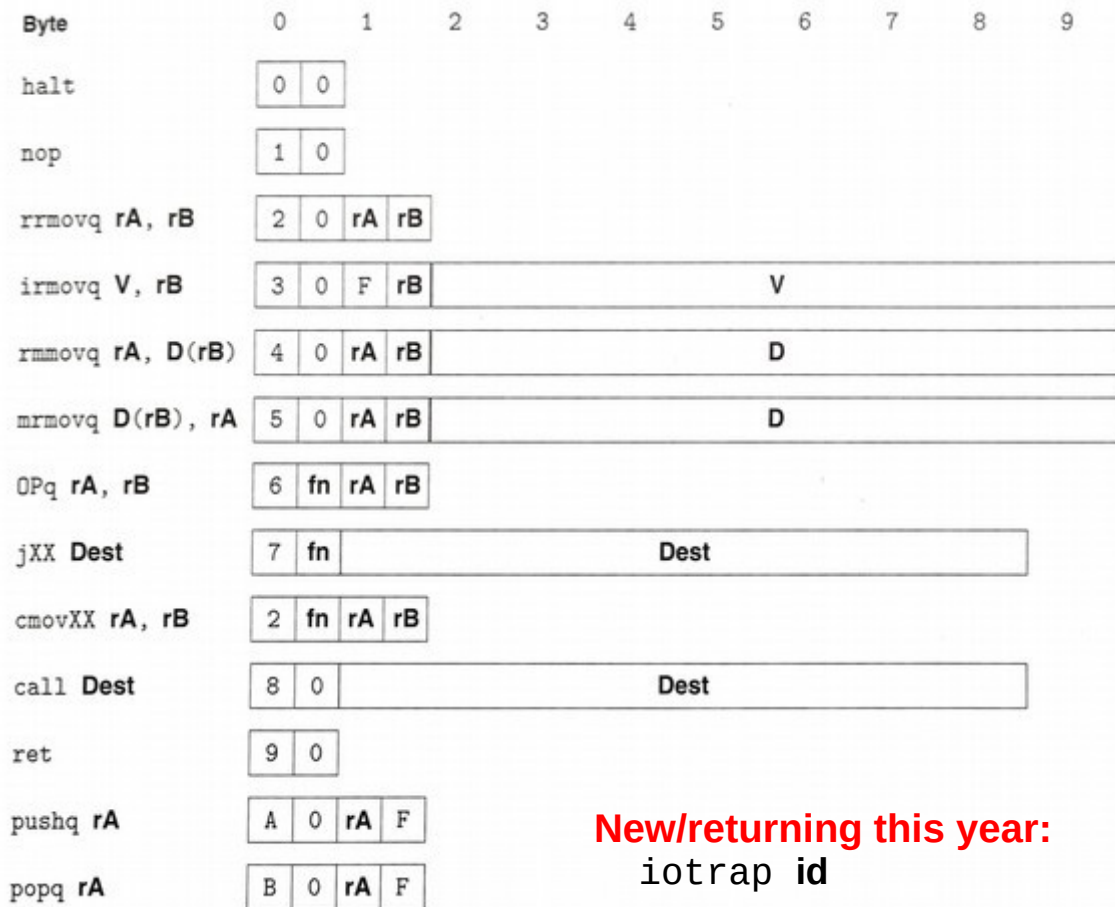
# Aside: Opcode Suffixes

- We've been assuming that the operand size suffix for opcodes is mandatory
  - E.g., the "l" or "q" in "movl" or "movq"
- Technically, it is only required if it cannot be inferred
  - E.g., `mov %eax, %edi` is not ambiguous
    - We can infer that this is a 32-bit move because of the destination
  - However, `mov $2, (%rdx)` is ambiguous
    - Is it a 8-bit move? 32 bits? 64 bits?
    - A suffix is required here (e.g., `movl $2, (%rdx)` for 32 bits)
  - Generally, it is safer always to include the suffix

# Aside: Memory Restrictions

- In x86-64, most opcodes have no memory -> memory form
  - I.e., you can't encode two memory operands in the same instruction
  - This is true for SSE/AVX instructions as well
  - Invalid: `movl (%rax), (%rdx)`
- Solution: use a temporary register
  - `movl (%rax), %ecx`
  - `movl %ecx, (%rdx)`

# Preview: Y86-64 ISA



**New/returning this year:**  
iotrap id

Number	Register name
0	%rax
1	%rcx
2	%rdx
3	%rbx
4	%rsp
5	%rbp
6	%rsi
7	%rdi
8	%r8
9	%r9
10	%r10
11	%r11
12	%r12
13	%r13
14	%r14

Value	Name	Meaning
1	AOK	Normal operation
2	HLT	halt instruction encountered
3	ADR	Invalid address encountered
4	INS	Invalid instruction encountered

RF: Program registers

%rax	%rsp	%r8	%r12
%rcx	%rbp	%r9	%r13
%rdx	%rsi	%r10	%r14
%rbx	%rdi	%r11	

Operations

addq	6 0
subq	6 1
andq	6 2
xorq	6 3

Branches

jmp	7 0	jne	7 4
jle	7 1	jge	7 5
jl	7 2	jg	7 6
je	7 3		

Moves

rrmovq	2 0	cmovne	2 4
cmovle	2 1	cmovge	2 5
cmovl	2 2	cmovg	2 6
cmove	2 3		

CC:  
Condition codes

ZF	SF	OF
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PC

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Stat: Program status

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DMEM: Memory

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