

# CS 261 Fall 2018

Mike Lam, Professor



## Memory

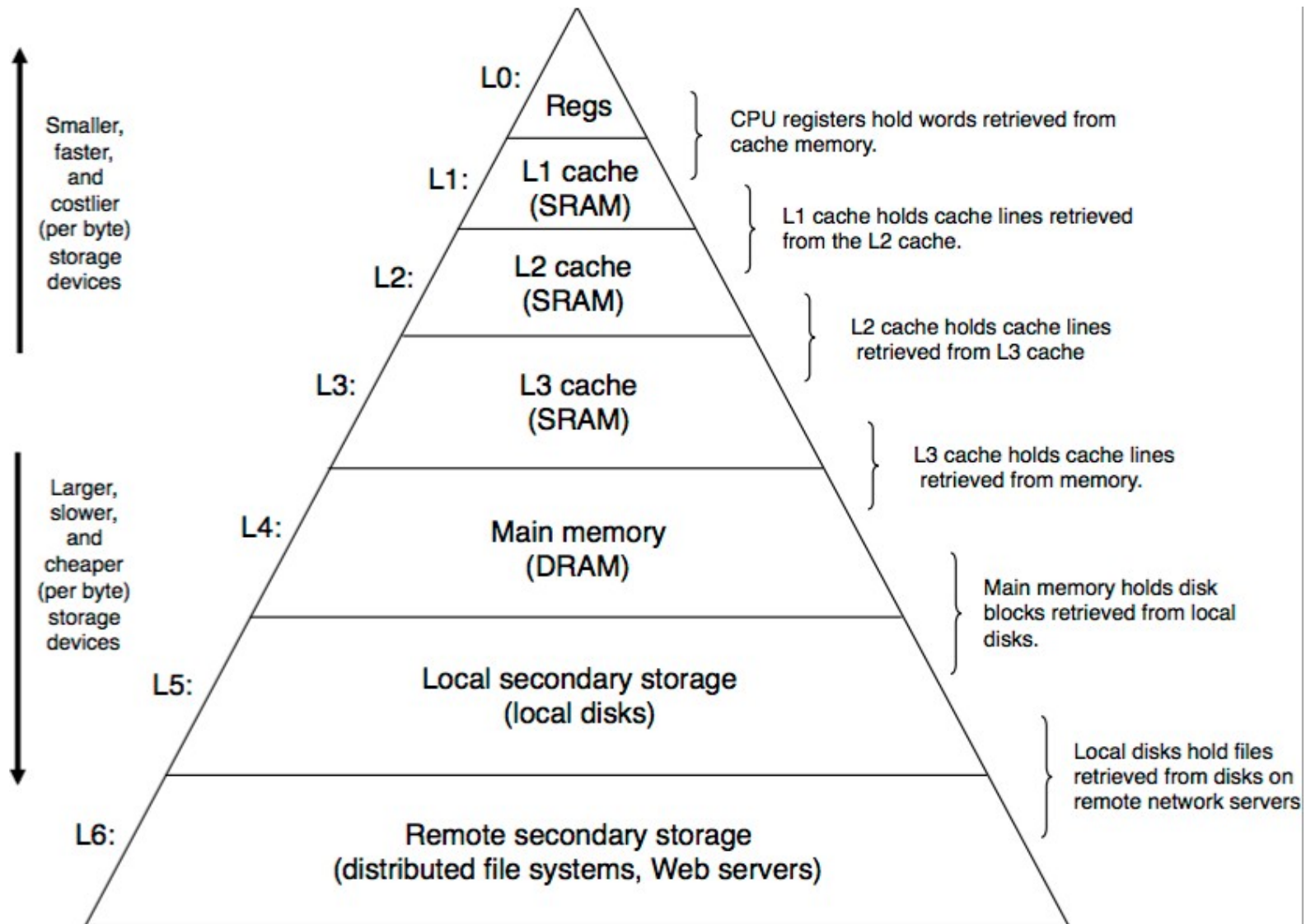
# Topics

- Memory hierarchy overview
- Storage technologies
- I/O architecture
- Storage trends
- Latency comparisons
- Locality

# Memory

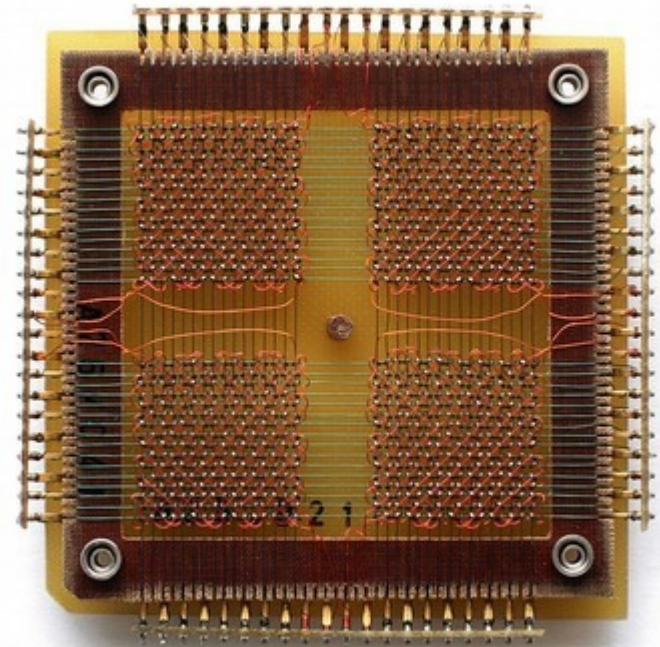
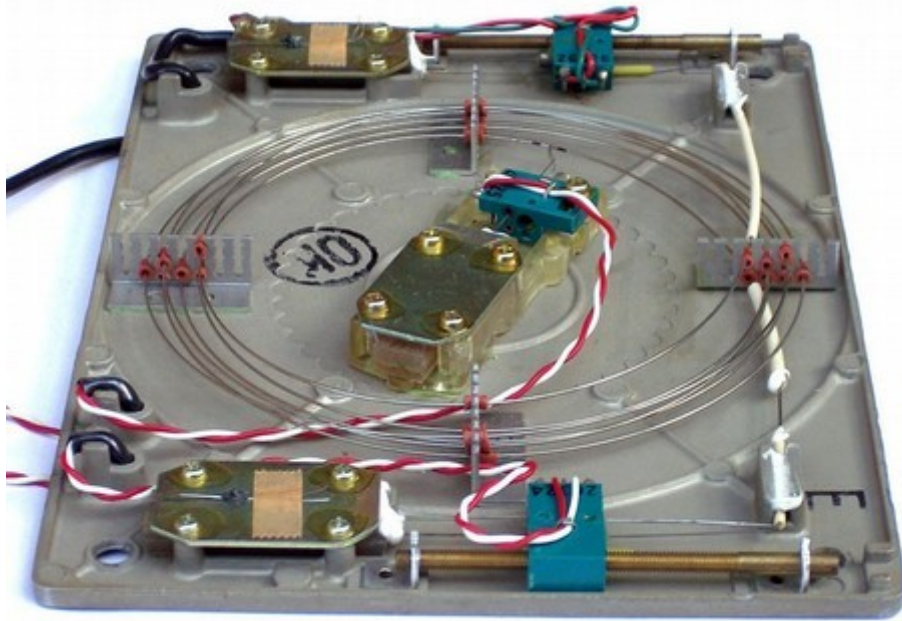
- Until now, we've referred to “memory” as a black box
- Modern systems actually have a variety of memory types called a **memory hierarchy**
  - Frequently-accessed data in faster memory
  - Each level **caches** data from the next lower level
- Goal: large general pool of memory that performs *almost* as well as if it was **all** made of the fastest memory
- Key concept: **locality** of time and space
- Other useful distinctions:
  - **Volatile** vs. **non-volatile**
  - **Random access** vs **sequential access**

# Memory hierarchy



# History

- Delay-line memory (volatile, sequential)
- Magnetic core memory (non-volatile, random-access)



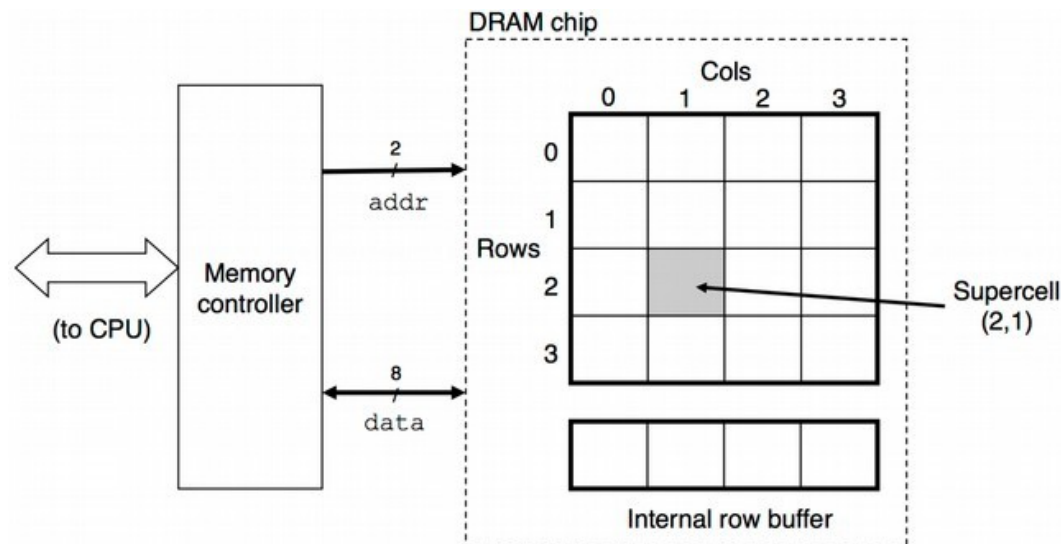
# RAM

- **Random Access Memory**
  - Smaller pools of fast memory, closer to the CPU
  - **Volatile**: eventually lose data if the supply voltage is turned off
  - **Static RAM (SRAM)**
    - Six transistors per bit in a circuit w/ feedback loops
    - Essentially the same as discussed in Ch. 4
    - Used for CPU caches; usually <1GB
  - **Dynamic RAM (DRAM)**
    - One capacitor per bit with a single access transistor
    - Must be refreshed periodically
    - Used for main memory and graphics memory
    - Usually <64 GB



# DRAM

- DRAM chips store data in a grid of **supercells**
- **Memory controller** used to access data
  - Connected to CPU via memory bus
  - Row access strobe (RAS) request
  - Column access strobe (CAS) request



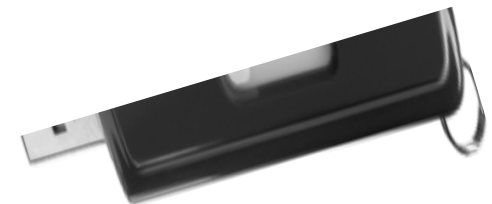
# Enhanced DRAM

- **Fast page mode DRAM (FPM DRAM)**
  - Serve same-row accesses from a row buffer
- **Extended data out DRAM (EDO DRAM)**
  - Allow CAS signals to be more closely spaced
- **Synchronous DRAM (SDRAM)**
  - Use a clock to synchronize and speed accesses
- **Double data-rate SDRAM (DDR SDRAM)**
  - Use both rising and falling edges of clock signal
- **Video RAM (VRAM)**
  - Shift an entire buffer's contents in a single operation
  - Allow simultaneous reads and writes



# Nonvolatile memory

- **Nonvolatile memory** retains data if the supply voltage is turned off
  - Historically referred to as **read-only memory** (ROM)
  - Newer forms of nonvolatile memory can be written
- **Programmable ROM** (PROM)
  - Programmed only once by blowing fuses
- **Erasable PROM** (EPROM)
  - Re-programmed using ultraviolet light
- **Electrically-erasable PROM** (EEPROM)
  - Re-programmed using electric signals
  - Basis for **flash memory** storage devices



# Non-volatile SRAM

- **Battery-backed SRAM (BBSRAM)**
  - External battery maintains value when power is off
- **Non-volatile SRAM (nvSRAM)**
  - Handles reads and writes the same as SRAM
  - Non-volatile component for permanent storage
  - Capacitor provides energy to store if current is lost

# Disk storage

- **Disk storage** systems hold large amounts of data
  - More cost effective than SRAM or DRAM
  - Usually order of magnitudes slower
- **Solid-state drives (SSDs)**
  - Flash memory organized into blocks
- Traditional **magnetic hard disk drives (HDDs)**
  - Multiple **platters** with **surfaces** coated with magnetic material
  - Accessed using a physical arm with a magnetic head
  - Data stored on surface in **tracks** partitioned into **sectors**



# Hard disk drives

- Capacity is based on **areal density**
  - Product of **recording density** and **track density**
- Operation requires mechanical motion
  - Magnetic read/write head on an **actuator arm**
- Speed is based on average **access time**
  - Sum of **seek time**, **rotational latency**, and **transfer time**
  - Platters spin at standard rate
- **Disk controller** coordinates accesses
  - Maps **logical blocks** to (surface, track, sector) numbers

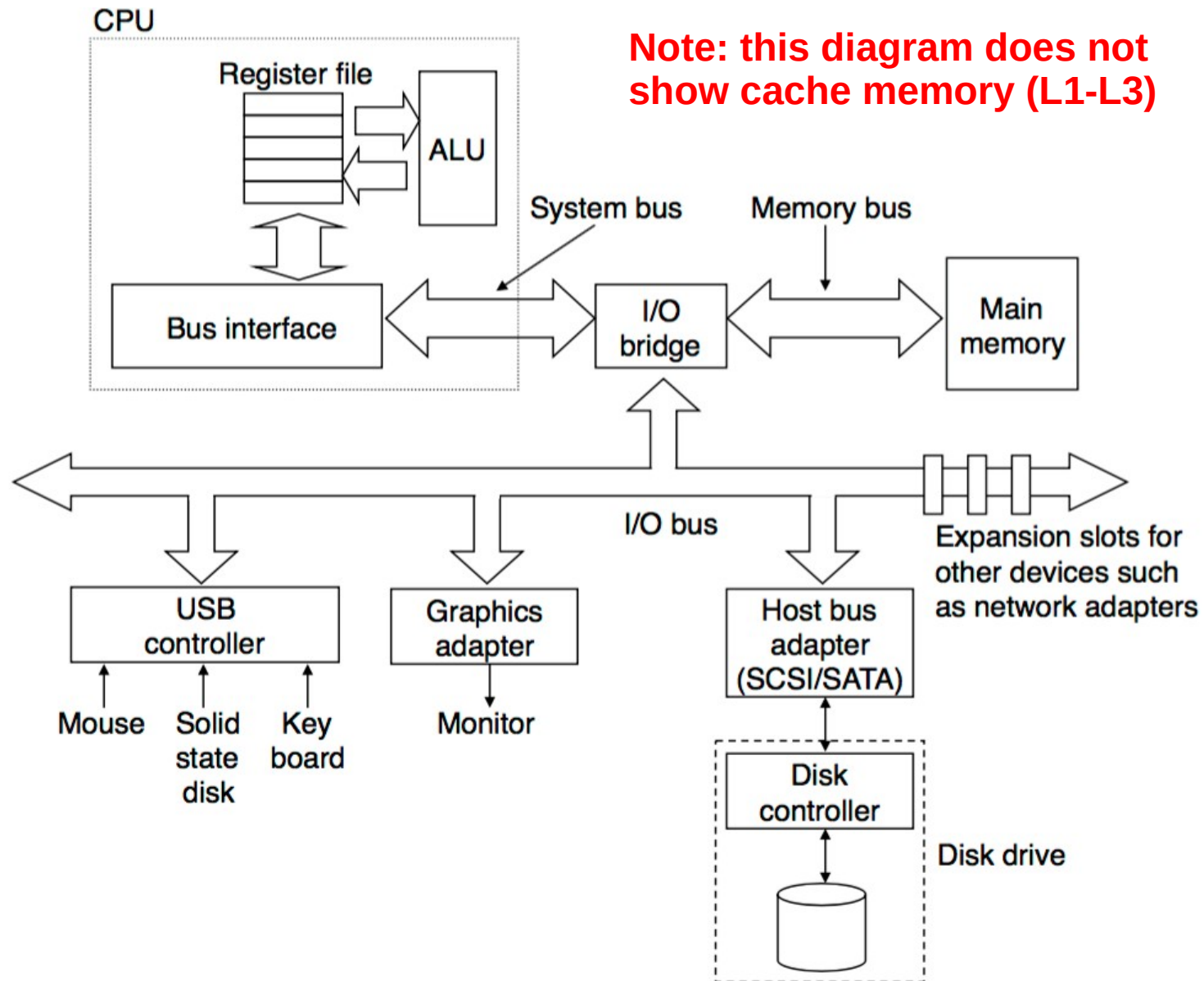


# Tape and network storage

- **Archival** storage systems provide large-scale data storage
  - Lowest cost per byte, but slowest access
- **Tape drives** store data on magnetic tape
  - Often in an off-site location for added redundancy
- **Network-attached storage** (NAS) systems
  - Dedicated data storage server
  - Often uses redundant disks for reliability (RAID)
  - Communicate over a network via a file sharing protocol
  - Examples: NFS, Samba, AFS
  - *More about this in CS 361 and CS 470!*



# I/O architecture

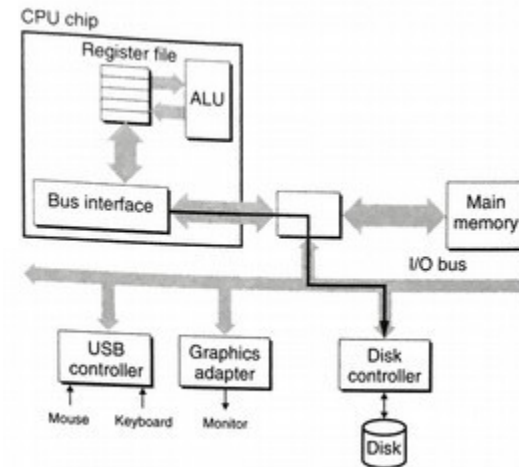


# I/O architecture

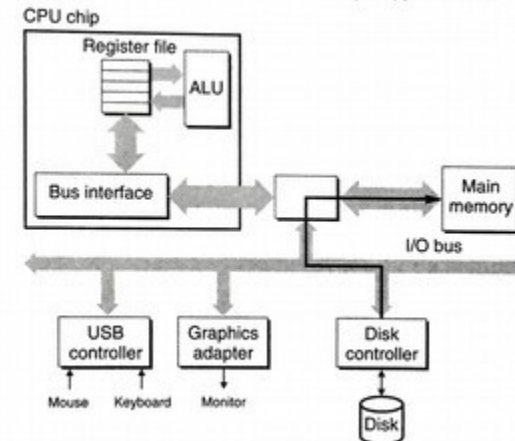
- **Cache memory** (SRAM)
  - Access via direct connection to CPU (or on-die)
- **Main memory** (DRAM)
  - **Bus transactions** via **I/O bridge** on motherboard
- **Disk drives** (magnetic disk & SSD)
  - Connected to I/O bridge via **I/O bus**
  - Requires a **device controller** for communication
  - Memory transactions w/o CPU via **direct memory access** (DMA)
  - Technologies: **USB**, **SATA**, **SCSI**
- **Other memory** (graphics, network storage)
  - Connected to I/O bus using **expansion slots** on motherboard

# DMA

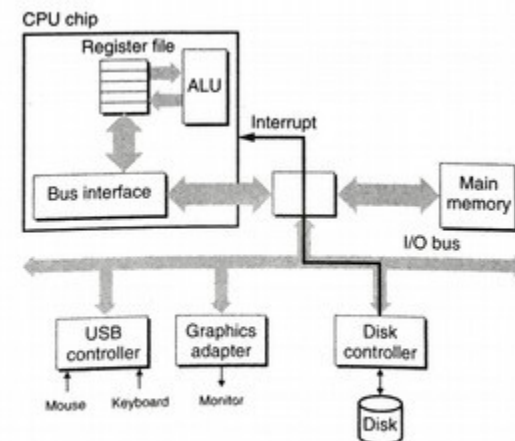
- 1) CPU initiates disk read
- 2) Disk reads data
- 3) Disk writes RAM via DMA
- 4) Disk notifies CPU



(a) The CPU initiates a disk read by writing a command, logical block number, and destination memory address to the memory-mapped address associated with the disk.



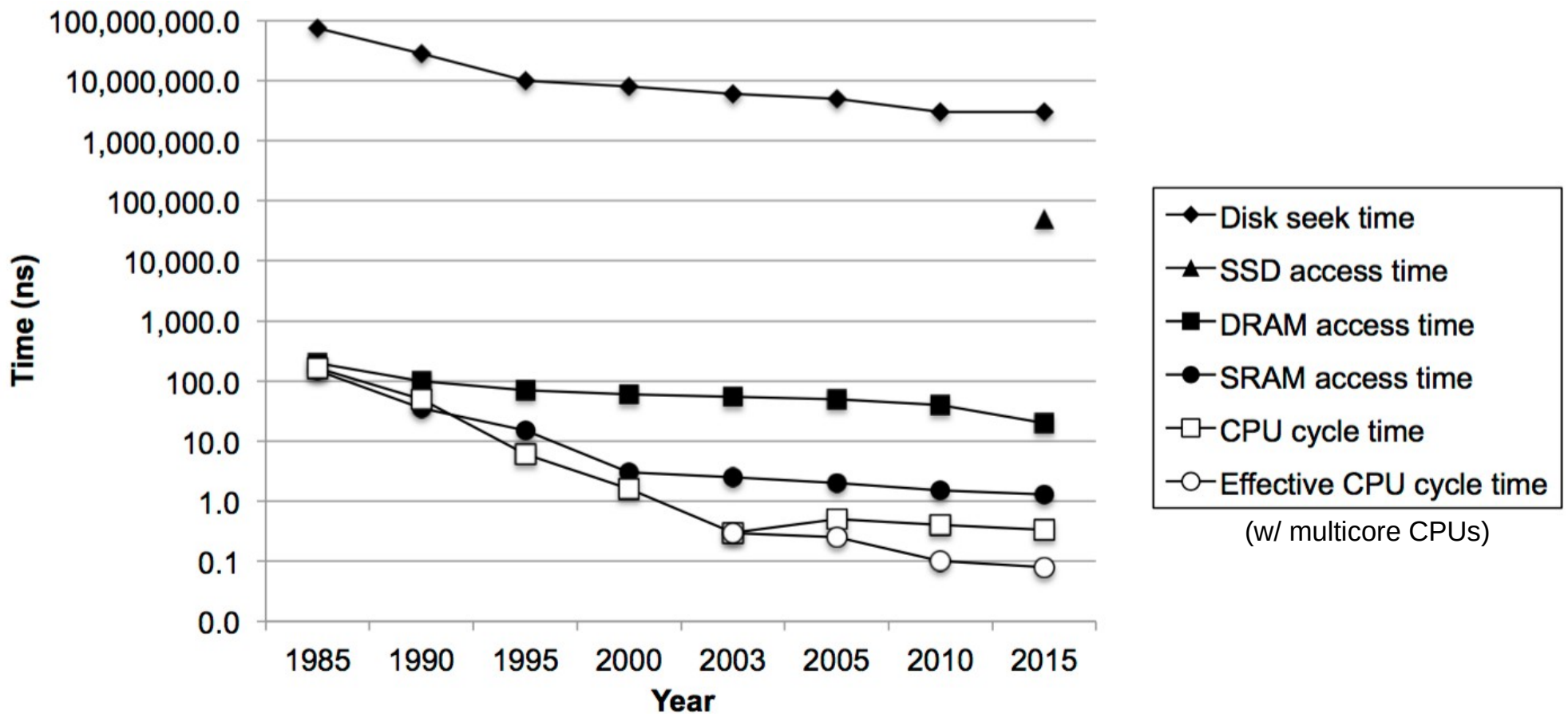
(b) The disk controller reads the sector and performs a DMA transfer into main memory.



(c) When the DMA transfer is complete, the disk controller notifies the CPU with an interrupt.



# Technology comparison



# Storage trends

Metric	1985	1990	1995	2000	2005	2010	2015	2015:1985
\$/MB	2,900	320	256	100	75	60	25	116
Access (ns)	150	35	15	3	2	1.5	1.3	115

## (a) SRAM trends

Metric	1985	1990	1995	2000	2005	2010	2015	2015:1985
\$/MB	880	100	30	1	0.1	0.06	0.02	44,000
Access (ns)	200	100	70	60	50	40	20	10
Typical size (MB)	0.256	4	16	64	2,000	8,000	16,000	62,500

## (b) DRAM trends

Metric	1985	1990	1995	2000	2005	2010	2015	2015:1985
\$/GB	100,000	8,000	300	10	5	0.3	0.03	3,333,333
Min. seek time (ms)	75	28	10	8	5	3	3	25
Typical size (GB)	0.01	0.16	1	20	160	1,500	3,000	300,000

## (c) Rotating disk trends

Metric	1985	1990	1995	2000	2003	2005	2010	2015	2015:1985
Intel CPU	80286	80386	Pent.	P-III	Pent. 4	Core 2	Core i7 (n)	Core i7 (h)	—
Clock rate (MHz)	6	20	150	600	3,300	2,000	2,500	3,000	500
Cycle time (ns)	166	50	6	1.6	0.3	0.5	0.4	0.33	500
Cores	1	1	1	1	1	2	4	4	4
Effective cycle time (ns)	166	50	6	1.6	0.30	0.25	0.10	0.08	2,075

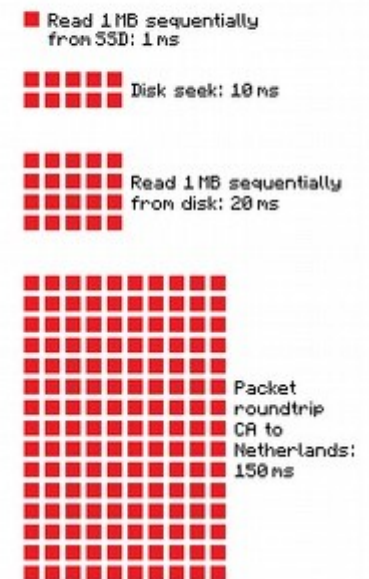
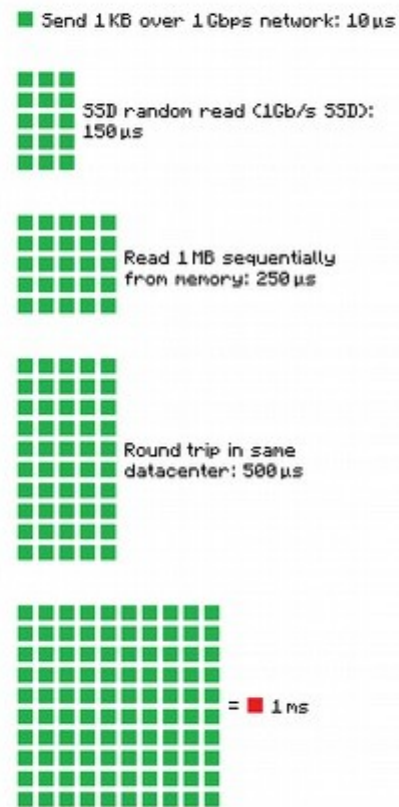
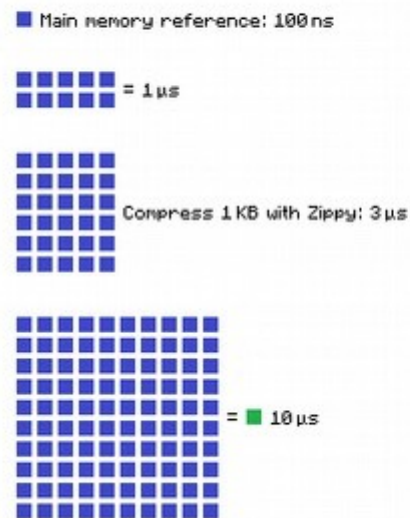
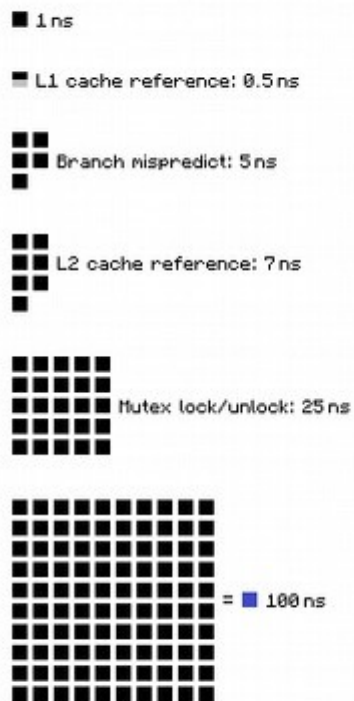
## (d) CPU trends

**Faster  
and  
cheaper**

**Effective cycle  
times continue  
to decrease**

# Latency comparison

## Latency Numbers Every Programmer Should Know



Source: <https://gist.github.com/2841832>

# Latency comparison

Lets multiply all these durations by a billion: (originally from <https://dzone.com/articles/every-programmer-should-know>)

## Minute:

L1 cache reference (0.5s) - *One heart beat*

L2 cache reference (7s) - *Long yawn*

## Hour:

Main memory reference (100s) - *Brushing your teeth*

## Day:

Send 2K bytes over 1 Gbps network (5.5 hr) - *From lunch to end of work day*

## Week:

SSD random read (1.7 days) - *A normal weekend*

Read 1 MB sequentially from memory (2.9 days) - *A long weekend*

Read 1 MB sequentially from SSD (11.6 days) - *Waiting for almost 2 weeks for a delivery*

## Year:

Disk seek (16.5 weeks) - *A semester in university*

Read 1 MB sequentially from disk (7.8 months) – *Two semesters in university*

The above 2 together (1 year)

## Decade:

Send packet CA->Netherlands->CA (4.8 years) - *Completing a bachelor's degree*

# Locality

- **Temporal locality**: frequently-accessed items will continue to be accessed in the future
  - Theme: **repetition is common**
- **Spatial locality**: nearby addresses are more likely to be accessed soon
  - Theme: **sequential access is common**
- Why do we care?
  - *Programs with good locality run faster than programs with poor locality*

# Data locality

- Temporal locality: keep often-used values in higher tiers of the memory hierarchy
- Spatial locality: use predictable access patterns
  - **Stride-1** reference pattern (**sequential** access)
  - **Stride-k** reference pattern (every k elements)
  - Closely related to **row-major** vs. **column-major**
  - Allows for **prefetching** (predicting the next needed element and preloading it)

# Instruction locality

- Normal execution exhibits spatial locality
  - Instructions execute **in sequence**
  - Long jumps exhibit poor locality (this includes calls)
- Loops exhibit both temporal and spatial locality
  - The body statements execute **repeatedly** (temporal locality) and **in sequence** (spatial locality)
  - Short loops are better

# Example

```
int64_t nums[4] = {
    0x12, 0x23,
    0x34, 0x45
};

for (size_t i = 0; i < 4; i++) {
    nums[i] += 1;
}
```

Memory address  
accesses:

- **0x200**
- **0x208**
- **0x210**
- **0x218**

```
        jmp _start

        .pos 0x100
_start:
    irmovq nums, %rcx      # rcx = nums
    irmovq 4, %rdx        # rdx = len(nums)
    irmovq 1, %rdi        # constant 1
    irmovq 8, %rsi        # constant 8

loop:
    mrmovq (%rcx), %rax    # rax = *rcx
    addq %rdi, %rax       # rax += 1
    rmmovq %rax, (%rcx)   # *rcx = rax

    addq %rsi, %rcx       # rcx += 8
    subq %rdi, %rdx       # rdi -= 1
    jne loop

        halt

        .pos 0x200
nums:
    .quad 0x12
    .quad 0x23
    .quad 0x34
    .quad 0x45
```



# Core themes

- **Systems design involves tradeoffs**
  - Memory: price vs. performance (e.g., DRAM vs. SRAM)
- **The details matter!**
  - Knowledge of the underlying system enables you to exploit latency inequalities for better performance
- Key concepts: **locality** and **caching**
  - Store and access related things together
  - Keep copies of things you'll need again soon
  - We'll look at these more next time