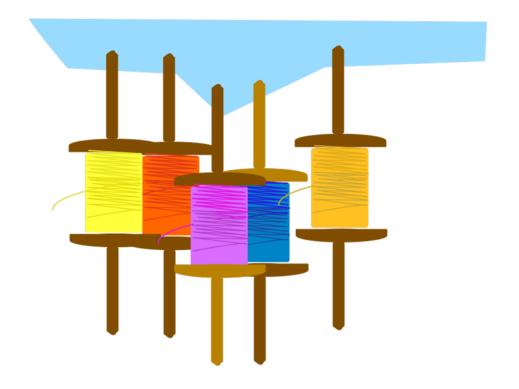
CS 261 Fall 2017

Mike Lam, Professor



Threads

Parallel computing

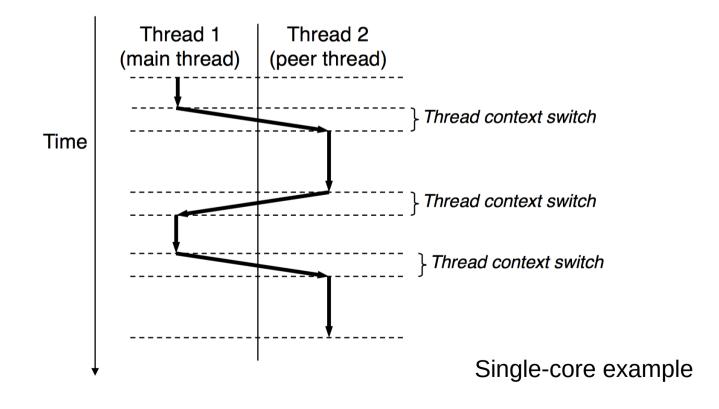
- Goal: concurrent or parallel computing
 - Take advantage of multiple hardware units to solve multiple problems simultaneously
- Motivations:
 - Maintain high utilization during slow I/O downtime
 - Maintain UI responsiveness during computation
 - Respond simultaneously to multiple realtime events
 - Split up a large problem and solve sub-pieces concurrently to achieve faster time-to-solution (strong scaling)
 - Solve larger problems by adding more hardware (weak scaling)

Parallel computing

- Process: currently-executing program
 - Code and state (PC, stack, data, heap)
 - Private address space
- Thread: unit of execution or logical flow
 - Exists within the context of a single process
 - Shares code/data/heap/files w/ other threads
 - Keeps private PC, stack, and registers
 - Stacks are technically shared, but harder to access

Threads

- One main thread for each process
 - Can create multiple peer threads

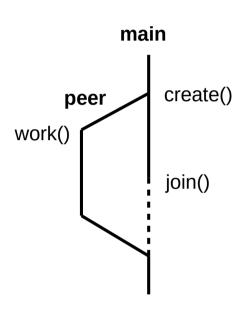


POSIX threads

- Pthreads POSIX standard interface for threads in C
 - Not part of the standard library
 - Requires "-lpthread" flag during linking
 - pthread_create: spawn a new child thread
 - pthread_t struct for storing thread info
 - attributes (or NULL)
 - thread work routine (function pointer)
 - thread routine parameter (void*, can be NULL)
 - pthread_self: get current thread ID
 - pthread_exit: terminate current thread
 - can also terminate implicitly by returning from the thread routine
 - pthread_join: wait for another thread to terminate

Thread creation example

```
#include <stdio.h>
#include <pthread.h>
void* work (void* arg)
    printf("Hello from work routine!\n");
    return NULL;
int main ()
    printf("Spawning single child ...\n");
    pthread_t child;
    pthread_create(&child, NULL, work, NULL);
    pthread_join(child, NULL);
    printf("Done!\n");
    return 0;
```



Shared memory

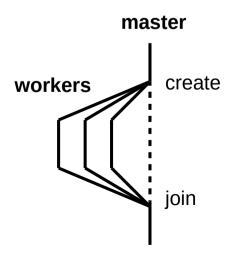
- Variables in threaded programs
 - Global variables (shared, single static copy)
 - Local variables (multiple copies, one on each stack)
 - Technically still shared if in memory, but harder to access
 - Not shared if cached in register
 - Safer to assume they're private; this is conventional
 - Local static variables (shared, single static copy)
 - Heap-allocated variables (shared, dynamic)

Processes vs. threads

- Process: currently-executing program
 - Code and state (PC, stack, data, heap)
 - Created via system call (fork); parent and child continue equally
 - Private address space not shared w/ other processes
 - Advantages: isolation, safety, and mutual exclusion
- Thread: unit of execution or logical flow
 - Exists within a process context
 - Created via library call (pthread_create); child runs separate routine
 - Shared address space w/ other threads
 - Private PC, registers, condition codes, and stack
 - Advantages: faster context switching, more shared resources

Parallel patterns

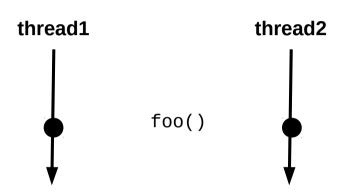
- Common pattern: master/worker threads
 - One original (main thread) creates multiple "child" threads
 - Each worker thread does a chunk of the work
 - Coordinate via shared global data structures
 - Keep as much data as possible local to the thread
 - Main thread waits for workers, then aggregates results



- Nondeterminism
- Data races and deadlock

```
foo:
    irmovq x, %rcx
    irmovq 7, %rax
    mrmovq (%rcx), %rdx
    addq %rax, %rdx
    rmmovq %rdx, (%rcx)
    ret

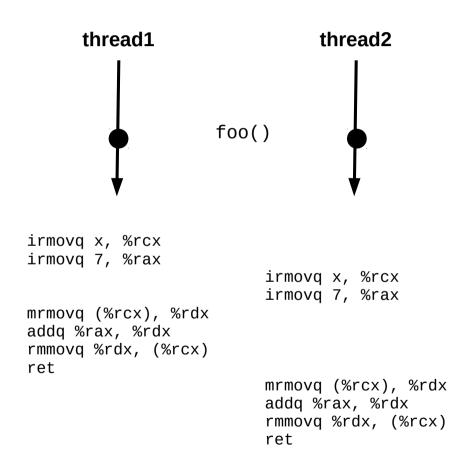
x:
    .quad 0
```



- Nondeterminism
- Data races and deadlock

```
ifoo:
    irmovq x, %rcx
    irmovq 7, %rax
    mrmovq (%rcx), %rdx
    addq %rax, %rdx
    rmmovq %rdx, (%rcx)
    ret

x:
    .quad 0
```

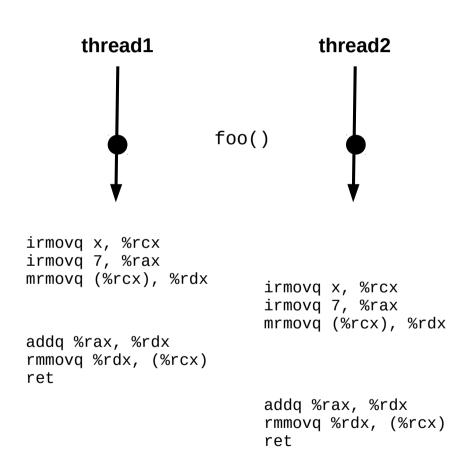


This interleaving is ok.

- Nondeterminism
- Data races and deadlock

```
foo:
    irmovq x, %rcx
    irmovq 7, %rax
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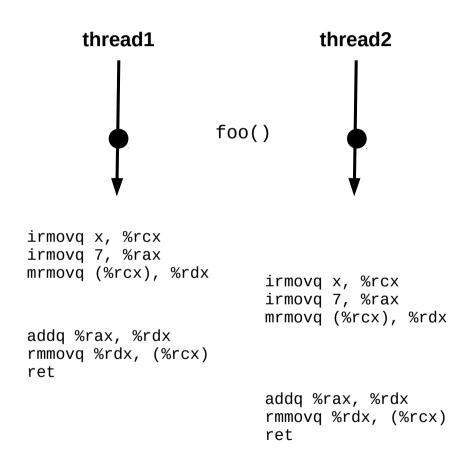
x:
    .quad 0
```



- Nondeterminism
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x:
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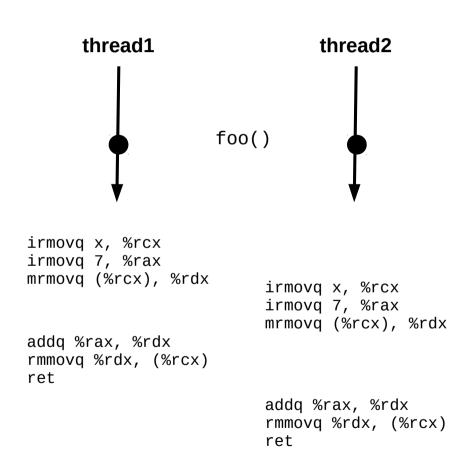


PROBLEM!

- Nondeterminism
- Data races and deadlock

```
foo:
    irmovq x, %rcx
    irmovq 7, %rax
    mrmovq (%rcx), %rdx
    addq %rax, %rdx
    rmmovq %rdx, (%rcx)
    ret

x:
    .quad 0
```



This will be a major topic in CS 361.

Mutual exclusion

- Fixing a data race requires some form of mutual exclusion
 - Only one thread at a time should update a particular memory region
 - In Pthreads, this can be accomplished using either a mutex or a semaphore (more details in CS 361)
 - However, these mechanism introduce overhead!
 - Threads must perform additional checks before updating memory
 - Some threads may have to pause and wait before they may continue
 - If not implemented carefully, the additional overhead may defeat the purpose of using multiple threads
 - Efficient parallel and distributed computing can be hard!

Automatic parallelism

- Wouldn't it be great if the compiler could automatically parallelize our programs?
 - This is a HARD problem
 - In some cases, it is (kind of) possible
 - Approach #1: code annotations in existing language
 - Example: OpenMP (CS 450, CS 470)
 - Approach #2: new language designed for parallelism
 - Example: HPF and Chapel (CS 430, CS 470)

```
int a[100];
#pragma omp parallel for
int i;
for (i=0; i < 100; i++)
    a[i] = i*i;</pre>
var a: [100] int;

forall i in 0..100 do
    a[i] = i*i;
```

OpenMP example

Chapel example

Parallel systems

- Uniprogramming / batch (1950s) CS 261
 - One process at a time w/ complete control of CPU
 - Minimal OS (mostly for launching programs)
- Multiprogramming / multitasking / time sharing (1960s) CS 261, CS 450
 - Multiple processes taking turns on a single CPU
 - Increased utilization, lower response time
 - OS handles scheduling and context switching
- (Symmetric) multiprocessing (1970s) CS 361, CS 450, CS 470
 - Multiple processes share multiple CPUs or cores
 - Increased throughput, increased parallelism
 - OS handles scheduling, context switching, and communication
- Distributed processing (1980s and onward) CS 361, CS 470
 - Multiple processes share multiple computers
 - Massive scaling; OS no longer sufficient (other middleware required)